

Errata

Chapter 1

p. 27₃ added material:

$$f(kT_s) = \frac{5}{3} (1 - e^{-0.916k}), \quad k = 0, 1, 2, \dots$$

change for

$$f(kT_s) = \frac{5}{3} (1 - e^{-0.916k}) = \frac{5}{3} \left(1 - \left(\frac{2}{5} \right)^k \right), \quad k = 0, 1, 2, \dots$$

p. 30, (1.4.6) delete $q^{-d}()$:

$$B(q^{-1}) = q^{-d}(b_1q^{-1} + b_2q^{-2} + \dots + b_mq^{-m})$$

change for

$$B(q^{-1}) = b_1q^{-1} + b_2q^{-2} + \dots + b_mq^{-m}$$

p. 29-30 errors is discretisation $T_s + 2$ change for $T_s + 1$

$$G(s) = \frac{Z_2}{(T_1s + 1)(T_2s + 2)}, \quad T_1 \neq T_2$$

change for

$$G(s) = \frac{Z_2}{(T_1s + 1)(T_2s + 1)}, \quad T_1 \neq T_2$$

4 changes in b_1, b_2, a_1, a_2 :

$$b_1 = Z_2T_1T_2 \left[- \left(e^{-\frac{T_s}{T_1}} + e^{-\frac{T_s}{T_2}} \right) - \frac{T_1(1 + e^{-\frac{T_s}{T_2}})}{T_2 - T_1} + \frac{T_2(1 + e^{-\frac{T_s}{T_1}})}{T_2 - T_1} \right]$$

$$b_2 = Z_2T_1T_2 \left[e^{-\frac{T_s}{T_1}} e^{-\frac{T_s}{T_2}} + \frac{T_1 e^{-\frac{T_s}{T_2}}}{T_2 - T_1} - \frac{T_2 e^{-\frac{T_s}{T_1}}}{T_2 - T_1} \right]$$

$$a_1 = - \left(e^{-\frac{T_s}{T_1}} + e^{-\frac{T_s}{T_1}} \right)$$

$$a_2 = e^{-\frac{T_s}{T_1}} e^{-\frac{T_s}{T_1}}$$

change for

$$\begin{aligned}
 b_1 &= Z_2 \left[- \left(e^{-\frac{T_s}{T_1}} + e^{-\frac{T_s}{T_2}} \right) - \frac{T_1(1 + e^{-\frac{T_s}{T_2}})}{T_2 - T_1} + \frac{T_2(1 + e^{-\frac{T_s}{T_1}})}{T_2 - T_1} \right] \\
 b_2 &= Z_2 \left[e^{-\frac{T_s}{T_1}} e^{-\frac{T_s}{T_2}} + \frac{T_1 e^{-\frac{T_s}{T_2}}}{T_2 - T_1} - \frac{T_2 e^{-\frac{T_s}{T_1}}}{T_2 - T_1} \right] \\
 a_1 &= - \left(e^{-\frac{T_s}{T_1}} + e^{-\frac{T_s}{T_2}} \right) \\
 a_2 &= e^{-\frac{T_s}{T_1}} e^{-\frac{T_s}{T_2}}
 \end{aligned}$$

Chapter 5

p. 209, (5.3.20) missing formula with this number – deleted number.

p. 212, (5.3.40) missing term:

$$= C \frac{A\Delta + \sum_{j=N_1}^{N_2} k_j z^{j-1} (B - G_j)}{\sum_{j=N_1}^{N_2} k_j}$$

change for

$$= C \frac{A\Delta + \sum_{j=N_1}^{N_2} k_j z^{j-1} (B - A\Delta G_j)}{\sum_{j=N_1}^{N_2} k_j}$$

p. 213, (5.3.53), (5.3.54) matrix \bar{C} must be inside:

$$G = \bar{C} \begin{pmatrix} \bar{B} & \mathbf{0} & \dots & \dots & \mathbf{0} \\ \bar{A}\bar{B} & \bar{B} & \mathbf{0} & \dots & \mathbf{0} \\ \vdots & & \ddots & \ddots & \vdots \\ \vdots & & & \bar{B} & \mathbf{0} \\ \bar{A}^{N_2-1}\bar{B} & \dots & & \dots & \bar{B} \end{pmatrix}$$

and

$$\mathbf{y}_0 = \bar{C} \begin{pmatrix} \bar{A} \\ \bar{A}^2 \\ \vdots \\ \bar{A}^{N_2} \end{pmatrix} \bar{\mathbf{x}}(k)$$

change for

$$G = \begin{pmatrix} \bar{C}\bar{B} & 0 & \dots & \dots & 0 \\ \bar{C}\bar{A}\bar{B} & \bar{C}\bar{B} & 0 & \dots & 0 \\ \vdots & & \ddots & \ddots & \vdots \\ \vdots & & & \bar{C}\bar{B} & 0 \\ \bar{C}\bar{A}^{N_2-1}\bar{B} & \dots & & \dots & \bar{C}\bar{B} \end{pmatrix}$$

and

$$\mathbf{y}_0 = \begin{pmatrix} \bar{C}\bar{A} \\ \bar{C}\bar{A}^2 \\ \vdots \\ \bar{C}\bar{A}^{N_2} \end{pmatrix} \bar{\mathbf{x}}(k)$$

p. 221, (5.5.8) added reference to the matrix inversion lemma, incorrect sign in the element (2,2) of the inverse matrix:

The block matrix inversion formula states

$$\begin{pmatrix} A^{-1} & D \\ C & B \end{pmatrix}^{-1} = \begin{pmatrix} A + AD\Delta CA & -AD\Delta \\ -\Delta CA & -\Delta \end{pmatrix}, \quad \Delta^{-1} = B - CAD$$

change for

The block matrix inversion formula states (see its proof of Lemma 2.3.1 on page 58)

$$\begin{pmatrix} A^{-1} & D \\ C & B \end{pmatrix}^{-1} = \begin{pmatrix} A + AD\Delta CA & -AD\Delta \\ -\Delta CA & \Delta \end{pmatrix}, \quad \Delta^{-1} = B - CAD$$

p. 229, Fig. 5.7.1 typo: N_1 change for N_2 .